

**Dr Satvir Singh**

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# **LINEAR INTEGRATED CIRCUITS**

**3-10**

**RC Phase Shift Oscillator**

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# Oscillator Principle

Oscillator must satisfy following Barkhausen's criteria:

- (1) Loop Gain must be unity ( $\beta A = 1$ )
- (2) Loop phase shift must be  $0^\circ$  or  $360^\circ$

$$v_i = v_{in} + v_f$$

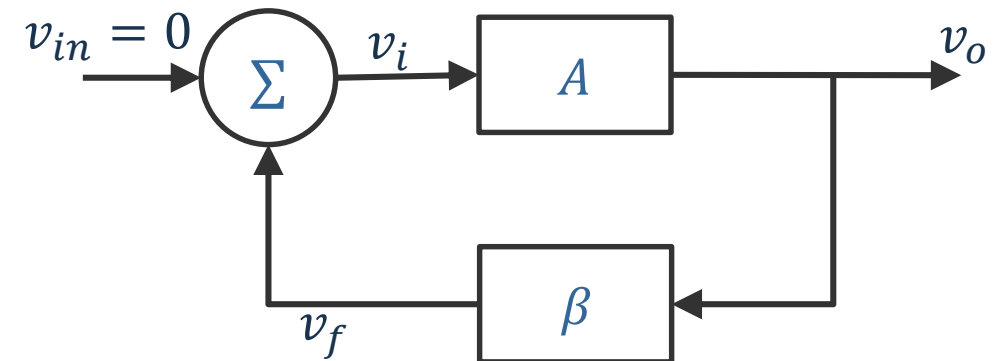
$$v_{in} = v_i - v_f$$

Since,  $v_f = \beta v_o$  and  $v_o = Av_i$

$$v_{in} = \frac{v_o}{A} - \beta v_o = v_o \left( \frac{1 - \beta A}{A} \right)$$

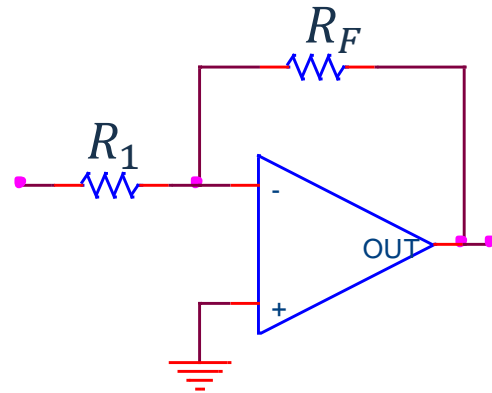
Overall gain after feedback is

$$A_F = \frac{v_o}{v_{in}} = \frac{A}{1 - \beta A}$$



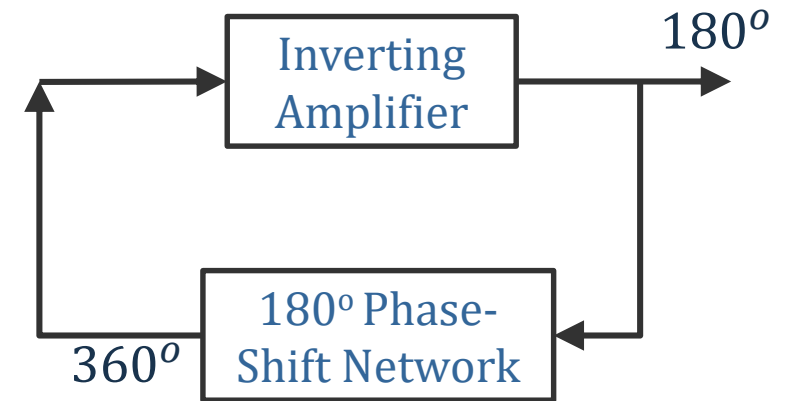
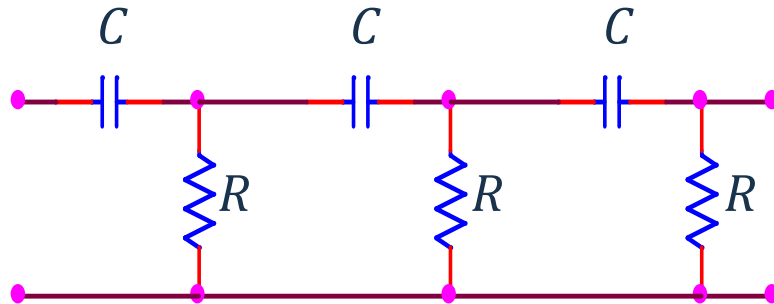
# Oscillator Circuit

Inverting Amplifier



$$\text{Gain } A = -\frac{R_F}{R_1}$$

Feedback Network



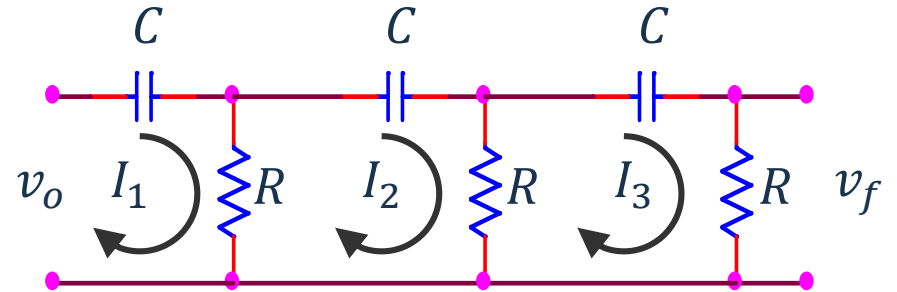
# Feedback Gain

Lets use Crammer's Rule to determine  $\beta = \frac{v_o}{v_f}$

$$\begin{bmatrix} R + \frac{1}{sC} & -R & 0 \\ -R & 2R + \frac{1}{sC} & -R \\ 0 & -R & 2R + \frac{1}{sC} \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix} = \begin{bmatrix} v_o \\ 0 \\ 0 \end{bmatrix}$$

$$D = \begin{bmatrix} R + \frac{1}{sC} & -R & 0 \\ -R & 2R + \frac{1}{sC} & -R \\ 0 & -R & 2R + \frac{1}{sC} \end{bmatrix} = \left( R + \frac{1}{sC} \right) \left[ \left( 2R + \frac{1}{sC} \right) \left( 2R + \frac{1}{sC} \right) - R^2 \right] + R \left( 2R + \frac{1}{sC} \right) + 0$$

$$D = \frac{1 + 5sCR + 6s^2C^2R^2 + s^3C^3R^3}{s^3C^3}$$



# Feedback Gain

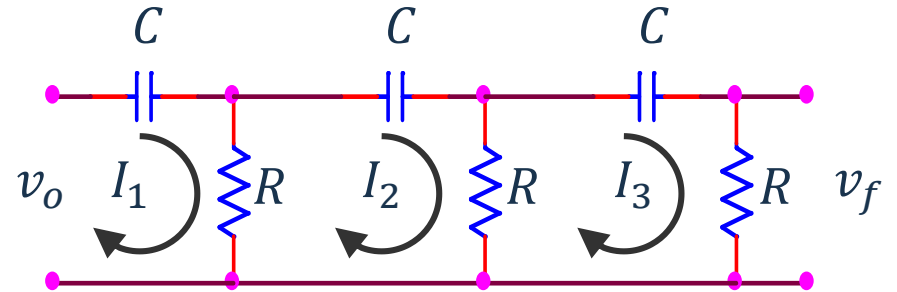
$$D_3 = \begin{bmatrix} R + \frac{1}{sC} & -R & v_o \\ -R & 2R + \frac{1}{sC} & 0 \\ 0 & -R & 0 \end{bmatrix} = v_o R^2$$

$$I_3 = \frac{D_3}{D} = \frac{s^3 C^3 v_o R^2}{1 + 5sCR + 6s^2 C^2 R^2 + s^3 C^3 R^3}$$

$$v_f = I_3 R = \frac{s^3 C^3 v_o R^3}{1 + 5sCR + 6s^2 C^2 R^2 + s^3 C^3 R^3}$$

Simplifying and putting  $s = j\omega$

$$\beta = \frac{v_f}{v_o} = \frac{s^3 C^3 R^3}{1 + 5sCR + 6s^2 C^2 R^2 + s^3 C^3 R^3} = \frac{j^3 \omega^3 C^3 R^3}{1 + 5j\omega CR + 6j^2 \omega^2 C^2 R^2 + j^3 \omega^3 C^3 R^3}$$



# Feedback Gain

We get

$$\beta = \frac{-j\omega^3 C^3 R^3}{1 + 5j\omega CR - 6\omega^2 C^2 R^2 - j\omega^3 C^3 R^3}$$

Dividing by  $-j\omega^3 C^3 R^3$  and assuming  $\alpha = 1/\omega CR$

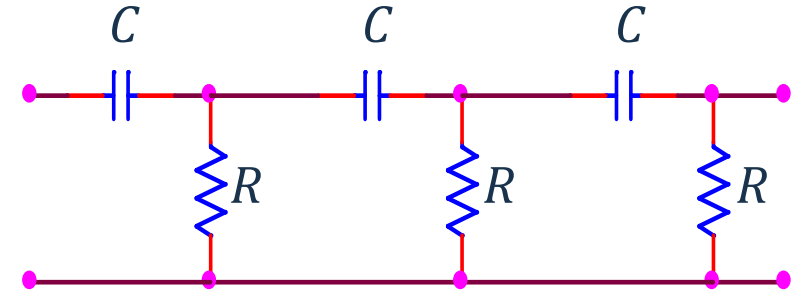
$$\beta = \frac{1}{j\alpha^3 - 5\alpha^2 - j6\alpha + 1} \quad (1)$$

For 180° phase difference imaginary part in (1) must be zero, i.e.,

$$\alpha^3 - 6\alpha = 0 \quad \Rightarrow \quad \alpha = \sqrt{6}$$

The frequency of oscillations is given by  $\alpha = 1/\omega CR = \sqrt{6}$

$$f_o = \frac{1}{2\pi RC\sqrt{6}} = \frac{0.065}{RC}$$



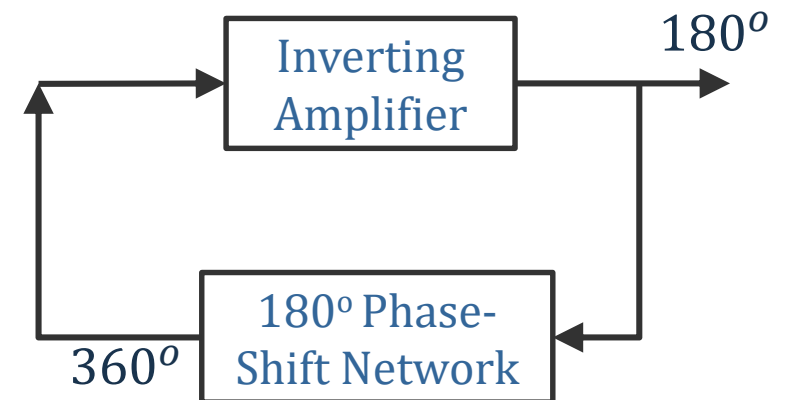
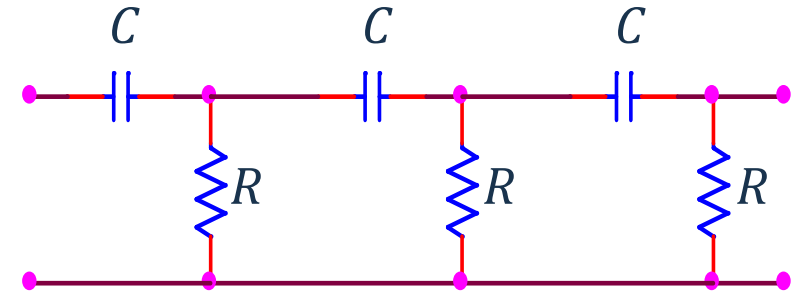
# Feedback Gain

The  $\beta$  at frequency of oscillations from (1)

$$\beta = \frac{1}{-5\alpha^2 + 1} = \frac{1}{-5(\sqrt{6})^2 + 1} = -\frac{1}{29}$$

Here, minus sign signifies  $180^\circ$  phase difference. Accordingly, for sustained oscillations the gain of the inverting amplifier must be

$$A = -\frac{R_F}{R_1} = -29$$



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**Thank You**

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